

Notice that in 1D problems, like the 1D infinite well or the 1D SHO, we only needed one number (n) to uniquely specify an eigenstate. This state label is called a **quantum number** or q-number and it is always in a 1-to-1 correspondence with the eigenvalues of an observable operator.

But in 3D problems, we need 3 quantum numbers (n_x, n_y, n_z) to fully specify a state [or equivalently (n, n_y, n_z), (n, n_x, n_z), etc where $n = \sqrt{n_x^2 + n_y^2 + n_z^2}$]. Just specifying n (or just n_x) is insufficient, since the eigenstates of \hat{H} (or \hat{H}_x) are degenerate. In cases with degeneracy, more than one quantum number is required to specify a state, and the other quantum numbers are associated with other operators that must commute with the first. If two operators commute (examples: $[\hat{H}, \hat{H}_x] = 0$, $[\hat{H}_x, \hat{H}_y] = 0$) then there exists a set of orthonormal simultaneous eigenstates of both operators. We proved this for the case of operators with non-degenerate states, but it is also true when there are degeneracies. (We will show below that when operators do not commute, it is impossible to find simultaneous eigenstates.)

Claim: If N quantum numbers [example: (n_x, n_y, n_z)] are required to uniquely specify a state, then there must exist N commuting operators [example: ($\hat{H}_x, \hat{H}_y, \hat{H}_z$)] whose simultaneous eigenstates are non-degenerate and whose N eigenvalues provide the quantum numbers that uniquely label the state. Such a set of operators is called a **complete set of commuting operators** (CSCO). We will give a proof later, when we talk about matrix formulation of QM.

Now that we have some familiarity w/ commutation relations, we can show how expectation values change w/ time:

Theorem: For any (linear hermitean) operator \hat{Q} (that does not depend on time)

$$\boxed{\frac{d}{dt} \langle Q \rangle = \frac{i}{\hbar} \langle [\hat{H}, \hat{Q}] \rangle}$$

Proof: $\frac{d}{dt} \langle Q \rangle = \frac{d}{dt} \langle \Psi | \hat{Q} \Psi \rangle = \langle \frac{\partial \Psi}{\partial t} | \hat{Q} \Psi \rangle + \langle \Psi | \frac{\partial}{\partial t} (\hat{Q} \Psi) \rangle$

Now, $\frac{\partial}{\partial t} (\hat{Q} \Psi) = \hat{Q} \frac{\partial \Psi}{\partial t}$ (since \hat{Q} assumed t -independ.)

$$\Rightarrow \frac{d}{dt} \langle Q \rangle = \langle \frac{\partial \Psi}{\partial t} | \hat{Q} \Psi \rangle + \langle \Psi | \hat{Q} \frac{\partial \Psi}{\partial t} \rangle$$

$$\frac{\partial \Psi}{\partial t} = -\frac{i}{\hbar} \hat{H} \Psi \quad (\text{TDSE}) \quad \Rightarrow$$

$$\frac{d \langle Q \rangle}{dt} = \underbrace{+\frac{i}{\hbar} \langle \hat{H} \Psi | \hat{Q} \Psi \rangle}_{\langle \Psi | \hat{H} \hat{Q} \Psi \rangle \text{ since } \hat{H} \text{ hermitean}} - \frac{i}{\hbar} \langle \Psi | \hat{Q} \hat{H} \Psi \rangle$$

Note: (+) not (-)

$$= \frac{i}{\hbar} \langle \Psi | (\hat{H} \hat{Q} - \hat{Q} \hat{H}) \Psi \rangle = \frac{i}{\hbar} \langle [\hat{H}, \hat{Q}] \rangle \quad \checkmark$$

So any observable Q whose operator \hat{Q} commutes w/ the hamiltonian \hat{H} has $\langle Q \rangle = \langle \Psi | \hat{Q} \Psi \rangle =$ constant in time for any $\Psi(x, t)$

$$[\hat{H}, \hat{Q}] = 0 \Rightarrow \langle Q \rangle = \text{const} \Leftrightarrow Q \text{ is } \underline{\text{conserved}}.$$

In classical mech, conservation of $Q \Rightarrow Q = \text{const}$ for isolated system

In QM, conservation of $Q \Rightarrow \langle Q \rangle = \text{const}$

Classically, measured conserved $Q \Rightarrow$ get same Q everytime. But in QM, measure conserved Q , get one of the q_n 's ($\hat{Q} f_n = q_n f_n$). In QM, conservation of Q only evident if you make ~~repeated~~ many measurements on an ensemble of identical systems.

Examples: • $[\hat{H}, \hat{H}] = 0 \Rightarrow \frac{d}{dt} \langle E \rangle = 0$

$\Rightarrow \langle E \rangle = \text{const}$ (already knew this: $\langle E \rangle = \sum_n E_n |c_n|^2$)

• $[\hat{H}, \hat{x}] \neq 0 \Rightarrow \frac{d\langle x \rangle}{dt} \neq 0$

$\Rightarrow \langle x \rangle$ changes w/ time in general

$$[\hat{H}, \hat{x}] = \left[\frac{\hat{p}^2}{2m} + V(\hat{x}), \hat{x} \right] = \frac{1}{2m} [\hat{p}^2, \hat{x}]$$

$$= \frac{1}{2m} \left(\underbrace{\hat{p} [\hat{p}, \hat{x}]}_{-i\hbar} + \underbrace{[\hat{p}, \hat{x}] \hat{p}}_{-i\hbar} \right) = -\frac{i\hbar}{m} \hat{p}$$

$$\Rightarrow \boxed{\frac{d\langle x \rangle}{dt} = \frac{\langle \hat{p} \rangle}{m}}$$

~ example of Ehrenfest's Thm:
Expectation values obey
Classical Laws.

• Showed in HW, $[\hat{H}, \hat{p}_x] = i\hbar \frac{\partial V}{\partial x}$

$$\Rightarrow \frac{d\langle p_x \rangle}{dt} = \left\langle -\frac{\partial V}{\partial x} \right\rangle \quad \sim \text{Ehrenfest again}$$

(classical: $dp/dt = F_{\text{net}} = -\partial V / \partial x$)

Heisenberg

The Uncertainty Principle

Recall standard deviation $\sigma_a = \sqrt{\sigma_a^2} = \sqrt{\langle (\hat{a} - \langle a \rangle)^2 \rangle}$

Classically, for any random variable x :

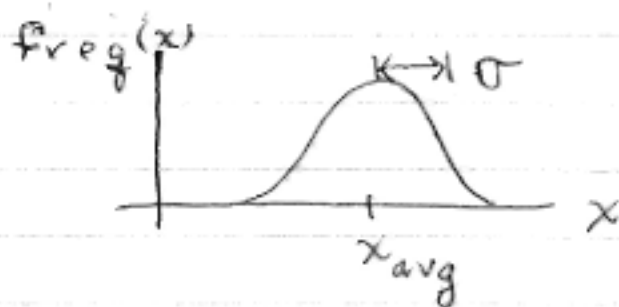
$$\langle x \rangle = x_{\text{avg}}$$

$$x - \langle x \rangle = \text{deviation}$$

$$\langle x - \langle x \rangle \rangle = \text{avg deviation} = 0$$

$$\langle (x - \langle x \rangle)^2 \rangle = \text{avg (deviation)}^2 \neq 0$$

$$\sqrt{\langle (x - \langle x \rangle)^2 \rangle} \approx \text{rms deviation} \approx |\text{spread}| \text{ about avg}$$



Theorem (proof later) For any two (linear, hermit.) operators \hat{A} , \hat{B} :

$$\sigma_A \sigma_B \geq \frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle$$

~ "Generalized
Uncertainty
Principle"

Example: $\hat{A} = \hat{x}$, $\hat{B} = \hat{p}_x$

$$[\hat{x}, \hat{p}_x] = i\hbar \Rightarrow \sigma_x \sigma_p \geq \hbar/2$$

~ the original Heisenberg Uncertainty Principle

Often written (sloppily) $\Delta x \cdot \Delta p \approx \hbar$

\Rightarrow if x known precisely ($\Delta x \approx 0$), Δp very large
if p known precisely ($\Delta p \approx 0$), Δx very large

Note: large $\Delta p \Rightarrow$ large p (since, if p known small $\Rightarrow \Delta p$ small)

But if p large, then $KE = p^2/2m$ large. So, if Δx small (particle confined to small space) then $\Delta p \approx \hbar/\Delta x \approx p$ is large \Rightarrow energy is large:

$$KE = \frac{p^2}{2m} \gtrsim \frac{(\Delta p)^2}{2m} \approx \frac{\hbar^2}{2m(\Delta x)^2}$$

We saw this in grd state of particle in infinite square well: $E_{grd} = \hbar^2 \pi^2 / 2ma^2$

\Rightarrow it always takes a big energy to confine particle to a small space.

Note: The Uncertainty Principle does not refer to uncertainty in the mind of the observer. The uncertainty is in Nature. If the particle has a well-defined momentum, then it does not (can not) have a well-defined position.

Proof of Generalized Uncertainty Principle (same as in text):

$$\sigma_A^2 = \langle \Psi | (\hat{A} - \langle A \rangle)^2 | \Psi \rangle = \langle (\hat{A} - \langle A \rangle) \Psi | (\hat{A} - \langle A \rangle) \Psi \rangle \stackrel{\text{defines } f}{=} \langle f | f \rangle$$

$(\hat{A} - \langle A \rangle)$ hermitian

$$\sigma_B^2 = \langle g | g \rangle \quad \text{where } g = (\hat{B} - \langle B \rangle) \Psi$$

$$\sigma_A^2 \sigma_B^2 = \langle f | f \rangle \langle g | g \rangle \geq |\langle f | g \rangle|^2$$

Schwartz Inequality: $|\vec{A}|^2 |\vec{B}|^2 \geq |\vec{A} \cdot \vec{B}|^2$

$\underbrace{A^2 B^2 \cos^2 \theta}_{< 1}$

Now $\langle f | g \rangle$ is some complex nbr z , and

$$|z|^2 = (\text{Re } z)^2 + (\text{Im } z)^2 \geq (\text{Im } z)^2 = \left(\frac{z - z^*}{2i} \right)^2$$

$$\Rightarrow \sigma_A^2 \sigma_B^2 \geq \left(\frac{1}{2i} [\langle f|g \rangle - \langle g|f \rangle] \right)^2$$

$$\text{Now } \langle f|g \rangle = \langle (\hat{A} - \langle A \rangle) \Psi | (\hat{B} - \langle B \rangle) \Psi \rangle =$$

$$= \langle \hat{A} \hat{B} \rangle - \langle A \rangle \langle \hat{B} \rangle - \langle \hat{A} \rangle \langle B \rangle + \langle A \rangle \langle B \rangle$$

$$\text{(since } \langle \hat{A} \rangle = \langle \Psi | \hat{A} | \Psi \rangle = \langle A \rangle \text{ (real!)} \text{ and } \langle \hat{B} \rangle = \langle \Psi | \hat{B} | \Psi \rangle = \langle B \rangle \text{ etc.)}$$

$$\langle f|g \rangle = \langle \hat{A} \hat{B} \rangle - \langle A \rangle \langle B \rangle - \langle A \rangle \langle B \rangle + \langle A \rangle \langle B \rangle$$

$$= \langle \hat{A} \hat{B} \rangle - \langle A \rangle \langle B \rangle \quad \uparrow \text{Notation: } \langle A \rangle \equiv \langle \Psi | \hat{A} | \Psi \rangle = \langle \hat{A} \rangle$$

$$\text{Likewise } \langle g|f \rangle = \langle \hat{B} \hat{A} \rangle - \langle B \rangle \langle A \rangle$$

$$\Rightarrow \langle f|g \rangle - \langle g|f \rangle = \langle \hat{A} \hat{B} \rangle - \langle \hat{B} \hat{A} \rangle = \langle \hat{A} \hat{B} - \hat{B} \hat{A} \rangle = \langle [\hat{A}, \hat{B}] \rangle$$

$$\Rightarrow \sigma_A^2 \sigma_B^2 = \left(\frac{1}{2i} \langle [\hat{A}, \hat{B}] \rangle \right)^2 \quad \text{Done.}$$

In addition to the position-momentum U.P.:

$$\Delta x \cdot \Delta p \geq \hbar/2$$

there is the time-energy U.P.:

$$\Delta t \cdot \Delta E \geq \hbar/2 \quad (\text{Looks similar, but is quite different.})$$

In QM, time t is a parameter, not an observable. You don't measure "the time of a particle". There is no observable corresponding to time in (non-relativistic) QM.

$\Delta t \neq$ uncertainty in time measurement (there is no "expectation value of time")

$\Delta t =$ time interval for system "to change significantly" (made precise below)

Recall $\frac{d\langle Q \rangle}{dt} = \frac{i}{\hbar} \langle [\hat{H}, \hat{Q}] \rangle$ and $\sigma_A^2 \sigma_B^2 \geq \left(\frac{\langle [\hat{A}, \hat{B}] \rangle}{2i} \right)^2$

Take $\hat{A} = \hat{H}$, $\hat{B} = \hat{Q} \Rightarrow \sigma_H^2 \sigma_Q^2 \geq \left(\frac{1}{2i} \langle [\hat{H}, \hat{Q}] \rangle \right)^2$
 $= \left(\frac{1}{2i} \frac{\hbar}{i} \frac{d\langle Q \rangle}{dt} \right)^2$
 $= \left(\frac{\hbar}{2} \right)^2 \left(\frac{d\langle Q \rangle}{dt} \right)^2$

$\Rightarrow \sigma_H \sigma_Q \geq \frac{\hbar}{2} \frac{d\langle Q \rangle}{dt}$

Define $\Delta E = \sigma_H = (1 \text{ sigma})$ uncertainty in energy

Define $\Delta t = \frac{\sigma_Q}{\left| \frac{d\langle Q \rangle}{dt} \right|} \Rightarrow \sigma_Q = \left| \frac{d\langle Q \rangle}{dt} \right| \cdot \Delta t$

Δt is time required for $\langle Q \rangle$ to change by 1 std. dev. σ

Examples • If Ψ is energy eigenstate, E known exactly $\Rightarrow \Delta E = 0 \Rightarrow \Delta t = \infty$.

It takes forever for a stationary state to change.

• If Ψ is superposition of E -eigenstates, $E_1 + E_2$ say, then $\Delta E \approx |E_2 - E_1|$ and $\Delta t \approx \hbar / |E_2 - E_1|$. Consistent with

$$|\Psi|^2 = \frac{1}{2} |\Psi_1|^2 + \frac{1}{2} |\Psi_2|^2 + 2 \operatorname{Re}(\Psi_1^* \Psi_2) \cos\left(\frac{E_2 - E_1}{\hbar} t\right)$$

(Homework Set 3)